

High-precision Full-closed Circuit Servo

MINAS A4F Series



Perfect choice for full-closed control A-phase, B-phase feedback scale feedback can be set up

Advanced Gain Tuning

- Further Evolution in Real-Time Auto-Gain Tuning.

Agile and Intelligent

- Improved Damping Control handles all types of machines, from low to high stiffness machines with simple but solid operation.

Amazingly slim size

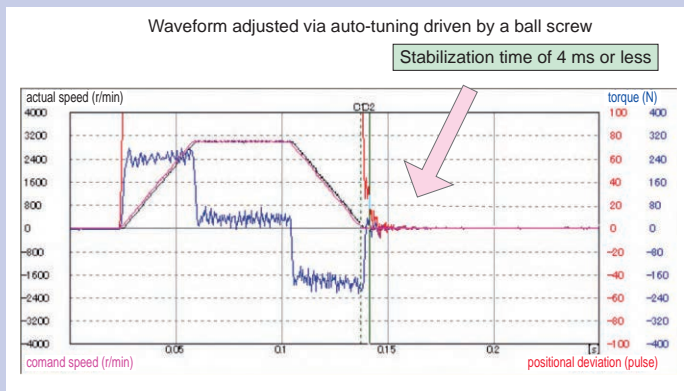
- Another Evolution in down-sizing, by 25% in size. (compared to A-series)

Details of Features

1. Further Adjustment-Free Operation

High-functionality Real-Time Auto-Gain Tuning

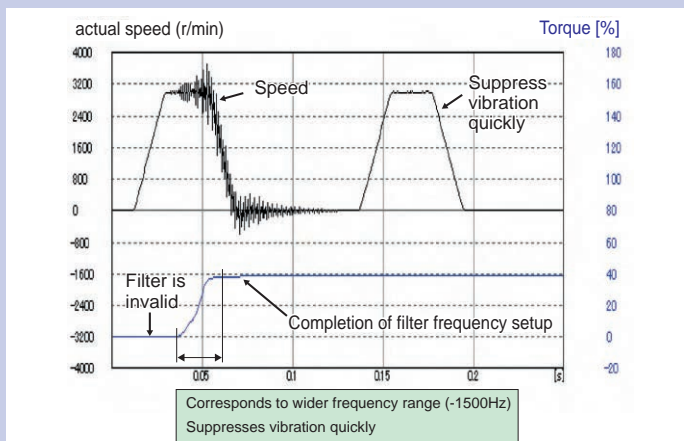
- Corresponds to even variation of load inertia. Offers real automatic gain tuning to low and high stiffness machines with a combination of an adaptive filter.
- Supports the vertical axis application where the load torque is different in rotational direction.
- Prevents the machine from over-traveling during automatic gain tuning with over-travel detecting function.
- Enables you to set and check while monitoring real-time automatic gain tuning conditions on the front panel.
- Real time high precision automatic tuning offers quick positioning of low stiffness machines, e.g. machine driven by belt, resonating machines, and high stiffness machines, e.g. machine driven by short ball screw.



2. Further Reduction of Vibration

Adaptive filter

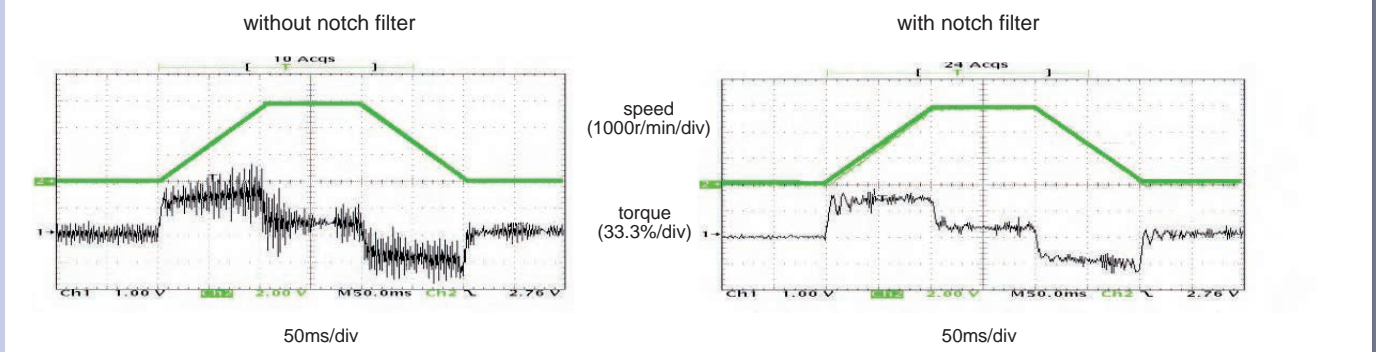
- Makes the notch filter frequency automatically follow the machine resonance frequency.
- Suppression of "Judder" noise of the machine can be expected which is caused by variation of the machines or resonance frequency due to aging.



2-channel notch filters

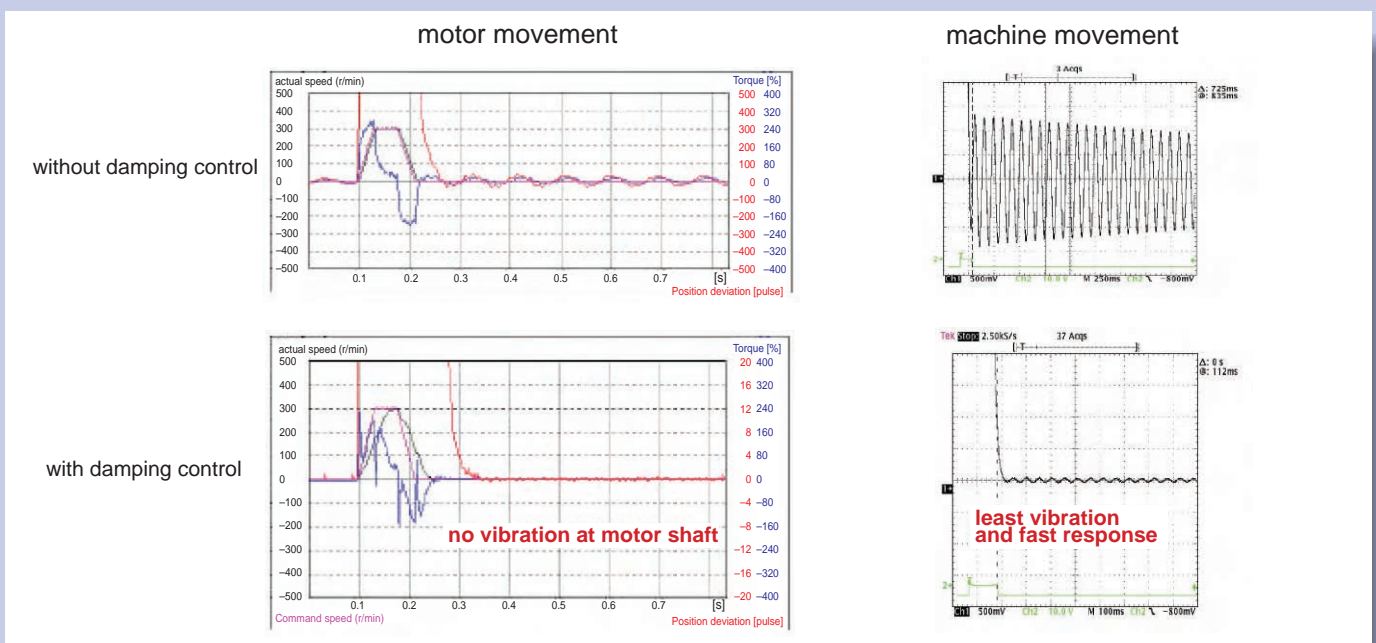
- 2-channel notch filters are equipped in the driver independent from adaptive filter.
- You can set up both frequency and width for each of 2 filters, and set up frequency in unit of 1Hz.
- Suppression of "Judder" noise of the machine which has multiple resonance points can be expected

Effect of notch filter



Damping control

- 2-channel damping filters are equipped in this driver. You can suppress vibration occurring at both starting and stopping in low stiffness machine, by manually setting up vibration frequency in 0.1Hz unit.
- You can also switch the vibration frequency set by 2-channel with rotating direction or with an external input to correspond to the variation of vibration frequency caused by the machine position.
- Easy setup with entry of only frequency and filter value. Improper setup values do not result in unstable operation



3. Further Flexibility and Multiplicity

Full-closed control (High precision positioning)

- Velocity response (bandwidth) of 1000Hz.
Damping control, Position command pulse 4Mpps.
- Position/Speed/Torque/Full-closed control.
- Feedback scale pulse (A-phase, B-phase) feedback can be connected.

Setup support with substantial monitoring function

- Faster communication speed of RS232/RS485 (Max.57600bps) establishes an easy and comfortable operating condition for setup support software, "PANATERM".
- Displays the factors of no-motor run and helps you to analyze the causes of troubles.
- You can set up the panel operation lock to inhibit the operation from the front panel, thus enables you to prevent miss-operation such as unintentional change of parameters.
*Note) Refer to page "F2" for setup support software.

Monitoring function with front panel

- LED display and analog monitor terminals are installed in the front panel.
- Displays "Motor speed" , "Motor torque" Position deviation" , "Motor load factor" and "Regeneration load factor" on LED.
- You can monitor "Motor speed" , "Motor torque" and "Position deviation" through analog monitor terminals.

Trial run (JOG)

- Features the function for trial (JOG) run through the front panel or console (option) without connecting to a host controller.
- You can shorten the machine setup time.

Inrush current suppressing function

- Inrush current suppressing resistor is equipped in this driver, which prevents the circuit breaker shutdown of the power supply caused by inrush current at power-on.
- Prevents unintentional shutdown of the power supply circuit breaker in multi-axes application and does not give load to the power line.

Regeneration discharging function

- Discharges the regenerative energy with resistor, which energy is generated while stopping the load with large moment of inertia, or use in up-down operation, and is returned to the driver from the motor.
- No regeneration discharge resistor is built-in to Frame A driver (MADDT1105F type.), Frame B driver (MBDDT2210F type.) and Frame G driver (MGDDTC3B4F type.) and we recommend you to connect optional regenerative resistor.
- Regenerative resistor is built-in to Frame C to F drivers, however, connection of the optional regenerative resistor bring you further regenerative capability.

Built-in dynamic brake

- You can select the dynamic brake action which short the servo motor windings of U, V and W, at Servo-OFF, CW/CCW over-travel inhibition, power shutdown and trip.
- You can select the action sequence setup depending on the machine requirement.

Setup support software

- With the setup support software, "PANATERM" via RS232/RS485 communication port, you can monitor the running status of the driver and set up parameters.
- You can read out the absolute position data of the motor with absolute encoder.

Wave-form graphic function

- With the setup support software, "PANATERM" , you can monitor the "Command speed" , "Actual speed" , "Torque" , "Position deviation" and "Positioning complete signal" .
- Helps you to analyze the machine and shorten the setup time
*Note) Refer to page "F2" for setup support software.

Torque limit value switching

- You can setup 2 torque limits and use them for tension control or press & hold control.
- It is possible to apply it to bumping homing.

SEMI F47 voltage sag immunity

- Features the function which complies to voltage sag immunity standard of SEMI F47 at no load or light load.
- Useful for semiconductor industry.

Notes)

- 1) Not applicable to single phase, 100V type.
- 2) Verify with the actual machine condition to F47, voltage sag immunity standard.

Frequency analyzing function

- You can confirm the response frequency characteristics of total machine mechanism including the servo motor with the setup support software, "PANATERM"
- Helps you to analyze the machine and shorten the setup time
*Note) Refer to page "F2" for setup support software.

Applicable overseas safety standards










Subject	Standard conformed		
Motor	IEC60034-1 IEC60034-5 UL1004 CSA22.2 No.100		Conforms to Low-Voltage Directives
	EN50178 UL508C CSA22.2 No.14		
Motor and driver	EN55011	Radio Disturbance Characteristics of Industrial, Scientific and Medical (ISM) Radio-Frequency Equipment	Conforms to references by EMC Directives
	EN61000-6-2	Immunity for Industrial Environments	
	IEC61000-4-2	Electrostatic Discharge Immunity Test	
	IEC61000-4-3	Radio Frequency Electromagnetic Field Immunity Test	
	IEC61000-4-4	Electric High-Speed Transition Phenomenon/ Burst Immunity Test	
	IEC61000-4-5	Lightening Surge Immunity Test	
	IEC61000-4-6	High Frequency Conduction Immunity Test	
	IEC61000-4-11	Instantaneous Outage Immunity Test	

I E C : International Electrotechnical Commission Pursuant to at the directive 2004/108/EC, article 9(2)
 E N : Europaischen Normen
 EMC : Electromagnetic Compatibility Panasonic Testing Centre
 U L : Underwriters Laboratories Panasonic Service Europe,
 CSA : Canadian Standards Association a division of Panasonic Marketing Europe GmbH
 Winsbergring 15, 22525 Hamburg, F.R. Germany

* When export this product, follow statutory provisions of the destination country.

Motor Line-up

	Motor series *	Rated output (kW)	Rated rotational speed (Max. speed) (r/min)	Rotary encoder		Brake	Gear	CE/UL	Enclosure	Features	Applications
				2500P/r incremental	17bit absolute/incremental	Holding	High precision				
Ultra low inertia	MAMA	0.1-0.75 4 models 0.1, 0.2, 0.4 and 0.75	5000 (6000)	○	○	○	—	○	IP65 (Except shaft through hole and connector)	·Small capacity ·Suitable for the machines directly coupled with high speed ball screw and high stiffness and high repetitive application	·SMT machines ·Inserters ·High repetitive positioning application
											
Low inertia	MSMD	0.05-0.75 5 models 0.05, 0.1, 0.2, 0.4 and 0.75	3000 (5000) *For 400W/100V and 750W 3000 (4500)	○	○	○	○	○	IP65 (Except shaft through hole and connector)	·Small capacity ·Suitable for all applications	·Inserters ·Belt driven machines ·Unloading robot
											
	MQMA (Cube type)	0.1-0.4 3 models 0.1, 0.2, and 0.4	3000 (5000) *For 400W/100V 3000 (4500)	○	○	○	—	○	IP65 (Except shaft through hole and connector)	·Small capacity ·Suitable for flat type and low stiffness machines with belt driven	·SMT machines ·Inserters ·Belt driven machines ·Unloading robot
											
	1.0-5.0 6 models 1.0,1.5,2.0, 3.0,4.0 and 5.0	3000 (5000) *For 4kW and 5kW 3000 (4500)	○	○	○	—	○	IP65 (Except cannon plug/connector pins)	·Middle capacity ·Suitable for the machines directly coupled with ball screw and high stiffness and high repetitive application	·SMT machines ·Inserter ·Food machines	
Middle inertia	MDMA	1.0-7.5 7 models 1.0,1.5,2.0, 3.0,4.0,5.0 and 7.5	2000 (3000) *For 7.5kW 1500 (3000)	○	○	○	—	○	IP65 (Except cannon plug/connector pins)	·Middle capacity ·Suitable for low stiffness machines with belt driven	·Belt driven machines ·Conveyers ·Robots
											
	MGMA (Low speed/High torque type)	0.9-6.0 5 models 0.9,2.0, 3.0,4.5 and 6.0	1000 (2000)	○	○	○	—	○	IP65 (Except cannon plug/connector pins)	·Middle capacity ·Suitable for machines requiring low speed with high torque	·Belt driven machines ·Conveyers ·Robots
											
	0.4-4.5 4 models 0.4,1.5, 2.5 and 4.5	2000 (3000)	○	○	○	—	○	IP65 (Except cannon plug/connector pins)	·Middle capacity ·Flat type and suitable for machines with space limitation	·Robots ·Food machines	
High inertia	MHMA	0.5-7.5 8 models 0.5,1.0,1.5, 2.0,3.0,4.0, 5.0 and 7.5	2000 (3000) *For 7.5kW 1500 (3000)	○	○	○	—	○	IP65 (Except cannon plug/connector pins)	·Middle capacity ·Suitable for low stiffness machines with belt driven, and large load moment of inertia	·Belt driven machines ·Conveyers ·Robots

* Motor is sharing with A4/A4P series

Model Designation

• Servo Motor

M S M D 5 A Z S 1 S * *

Symbol	Type
MAMA	Ultra low inertia (100W-750W)
MSMD	Low inertia (50W-750W)
MQMA	Low inertia (100W-400W)
MSMA	Low inertia (1.0kW-5.0W)
MDMA	Middle inertia (1.0kW-7.5kW)
MGMA	Middle inertia (900W-6.0kW)
MFMA	Middle inertia (400W-4.5kW)
MHMA	High inertia (500W-7.5kW)

Motor rated output

Symbol	Rated output	Symbol	Rated output
5A	50W	15	1.5kW
01	100W	20	2.0kW
02	200W	25	2.5kW
04	400W	30	3.0kW
05	500W	40	4.0kW
08	750W	45	4.5kW
09	900W	50	5.0kW
10	1.0kW	60	6.0kW
		75	7.5kW

Design order
1: Standard

Rotary encoder specifications

Symbol	Format	Pulse counts	Resolution	Wires
P	Incremental	2500P/r	10000	5
S	Absolute/ Incremental common	17bit	131072	7

Voltage specifications

Symbol	Specifications
1	100V
2	200V
Z	100V/200V common(50W only)

Special specifications

Motor structure

MSMD (standard stock), MQMA (build to order)

Symbol	Shaft		Holding brake		Oil seal	
	Round	Key-way, center tap	without	with	without	with*
A	●		●		●	
B	●			●	●	
S		●	●		●	
T		●		●	●	

* Motor with oil seal is manufactured by order.

MSMA, MDMA, MGMA, MFMA, MHMA

Symbol	Shaft		Holding brake		Oil seal	
	Round	Key-way	without	with	without	with
C	●		●			●
D	●			●		●
G		●	●			●
H		●		●		●

Products are standard stock items or build to order items. See index (page F31).

MAMA

Symbol	Shaft		Holding brake		Oil seal	
	Round	Key-way	without	with	without	with
A	●		●		●	
B	●			●	●	
E		●	●		●	
F		●		●	●	

Products are standard stock items or build to order items. See index (page F31).

See page, A4-77 for motor specifications

• Motor with reduction gear

M S M D 0 1 1 P 3 1 N

Symbol	Type
MSMD	Low inertia (100W-750W)

Motor rated output

Symbol	Rated output
01	100W
02	200W
04	400W
08	750W

Voltage specifications

Symbol	Specifications
1	100V
2	200V

Rotary encoder specifications

Symbol	Format	Pulse counts	Resolution	Wires
P	Incremental	2500P/r	10000	5
S	Absolute/ Incremental common	17bit	131072	7

Gear reduction ratio, gear type

Symbol	Gear reduction ratio	Motor output (W)				Gear type
		100	200	400	750	
1N	1 / 5	●	●	●	●	For high accuracy
2N	1 / 9	●	●	●	●	
3N	1 / 15	●	●	●	●	
4N	1 / 25	●	●	●	●	

Motor structure

Symbol	Shaft		Holding brake	
	Key-way	without	with	with
3	●	●		
4	●		●	●

See page, A4-133 for motor with gear reducer specifications

• Servo Driver

M A D D T 1 2 0 5 F * *

Special specifications

Driver specifications

Symbol	Specifications
F	Feedback scale pulse (A-phase, B-phase) full-closed control.

Frame symbol

Symbol	Frame
MADD	A4 series, Frame A
MBDD	A4 series, Frame B
MCDD	A4 series, Frame C
MDDD	A4 series, Frame D
MEDD	A4 series, Frame E
MFDD	A4 series, Frame F
MGDD	A4 series, Frame G

Power device Max. current rating

Symbol	Power device Max. current rating
T1	1.0A
T2	1.5A
T3	3.0A
T5	5.0A
T7	7.5A
TA	1.00A
TB	1.50A
TC	3.00A

Supply voltage specifications

Symbol	Specifications
1	Single phase, 100V
2	Single phase, 200V
3	3-phase, 200V
5	Single/3-phase, 200V

Current detector current rating

Symbol	Current detector, current rating
05	5A
07	7.5A
10	1.0A
20	2.0A
30	3.0A
40	4.0A
64	6.4A
90	9.0A
A2	1.20A
B4	2.40A

See page, A4-41 for driver specifications

Wiring example

Driver Frame Type Symbol (Frame A, B, C, D)

For details, refer to the Instruction Manual.

● Wiring of main circuit

Circuit Breaker (NFB)

Protects the power lines.
Shuts off the circuit when overcurrent passes.

Noise Filter (NF)

Prevents external noise from the power lines.
And reduces an effect of the noise generated by the servo driver.

Magnetic Contactor (MC)

Turns on/off the main power of the servo driver.
Surge absorber to be used together with this.

Reactor (L)

Reduces harmonic current of the main power.

<For safe operation>

When using reactors, install one reactor for each servo driver. (Do not use one reactor for two or more drivers.)

Pin RB1, RB2 and RB3 ...

- RB2 and RB3 to be kept shorted for normal operation.
- When the internal regenerative resistor capacity has shortage, disconnect between RB2 and RB3, then connect an external regenerative resistor between RB1 and RB2. (Note: that no regenerative resistor is equipped in Frame A and B type.)

Regenerative resistor (option)

Ground (Earth)

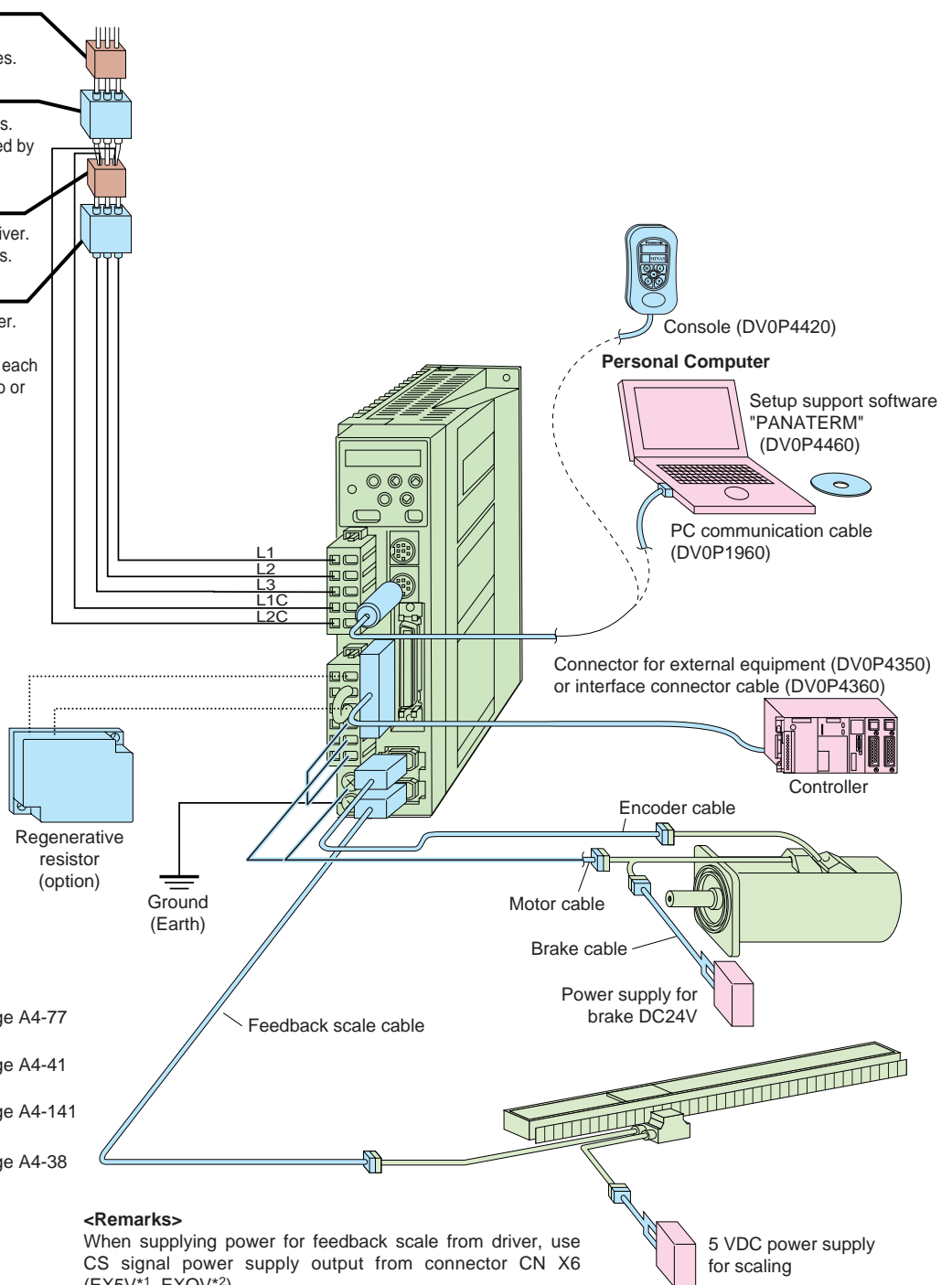
Motor	to page A4-77
Driver	to page A4-41
Option	to page A4-141
Recommended equipments	to page A4-38
Parts customer to prepare	

<Remarks>

When supplying power for feedback scale from driver, use CS signal power supply output from connector CN X6 (EX5V*1, EXOV*2).

*1 Current consumption of EX5V is 250 mA max.

*2 EXOV is connected to GND of the control circuit connected to CN X5. For wiring, refer to A4-45 and 46.



Driver Frame Type Symbol (Frame E, F)

For details, refer to the Instruction Manual.

● Wiring of main circuit

Circuit Breaker (NFB)

Protects the power lines.
Shuts off the circuit when overcurrent passes.

Noise Filter (NF)

Prevents external noise from the power lines.
And reduces an effect of the noise generated by the servo driver.

Magnetic Contactor (MC)

Turns on/off the main power of the servo driver.
Surge absorber to be used together with this.

Reactor (L)

Reduces harmonic current of the main power.

<For safe operation>

When using reactors, install one reactor for each servo driver. (Do not use one reactor for two or more drivers.)

P, B1 and B2 ...

- B1 and B2 to be kept shorted for normal operation.
- When the internal regenerative resistor capacity has shortage, disconnect between B1 and B2, then connect an external regenerative resistor between P and B2.

Regenerative resistor (option)

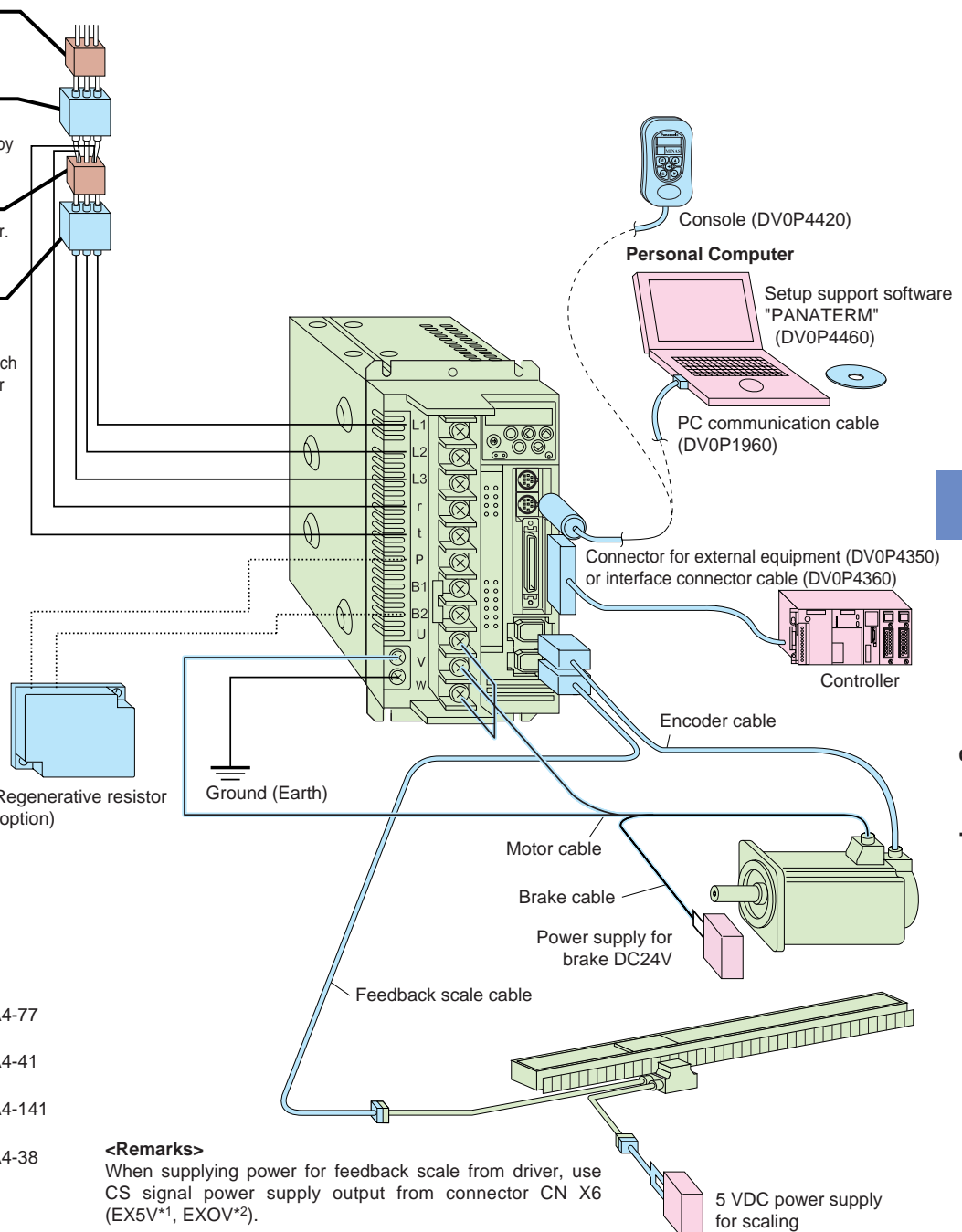
Motor	to page A4-77
Driver	to page A4-41
Option	to page A4-141
Recommended equipments	to page A4-38
Parts customer to prepare	

<Remarks>

When supplying power for feedback scale from driver, use CS signal power supply output from connector CN X6 (EX5V*1, EXOV*2).

*1 Current consumption of EX5V is 250 mA max.

*2 EXOV is connected to GND of the control circuit connected to CN X5. For wiring, refer to A4-45 and 46.



Wiring example

Driver Frame Type Symbol (Frame G)

For details, refer to the Instruction Manual.

● Wiring of main circuit

Magnetic Circuit Breaker (MCB)

Used to protect the power lines: overcurrent will shutoff the circuit.

Noise filter (NF)

Prevents external noise coming from the power line, or reduces noise generated by the servo motor.

Magnetic contactor (MC)

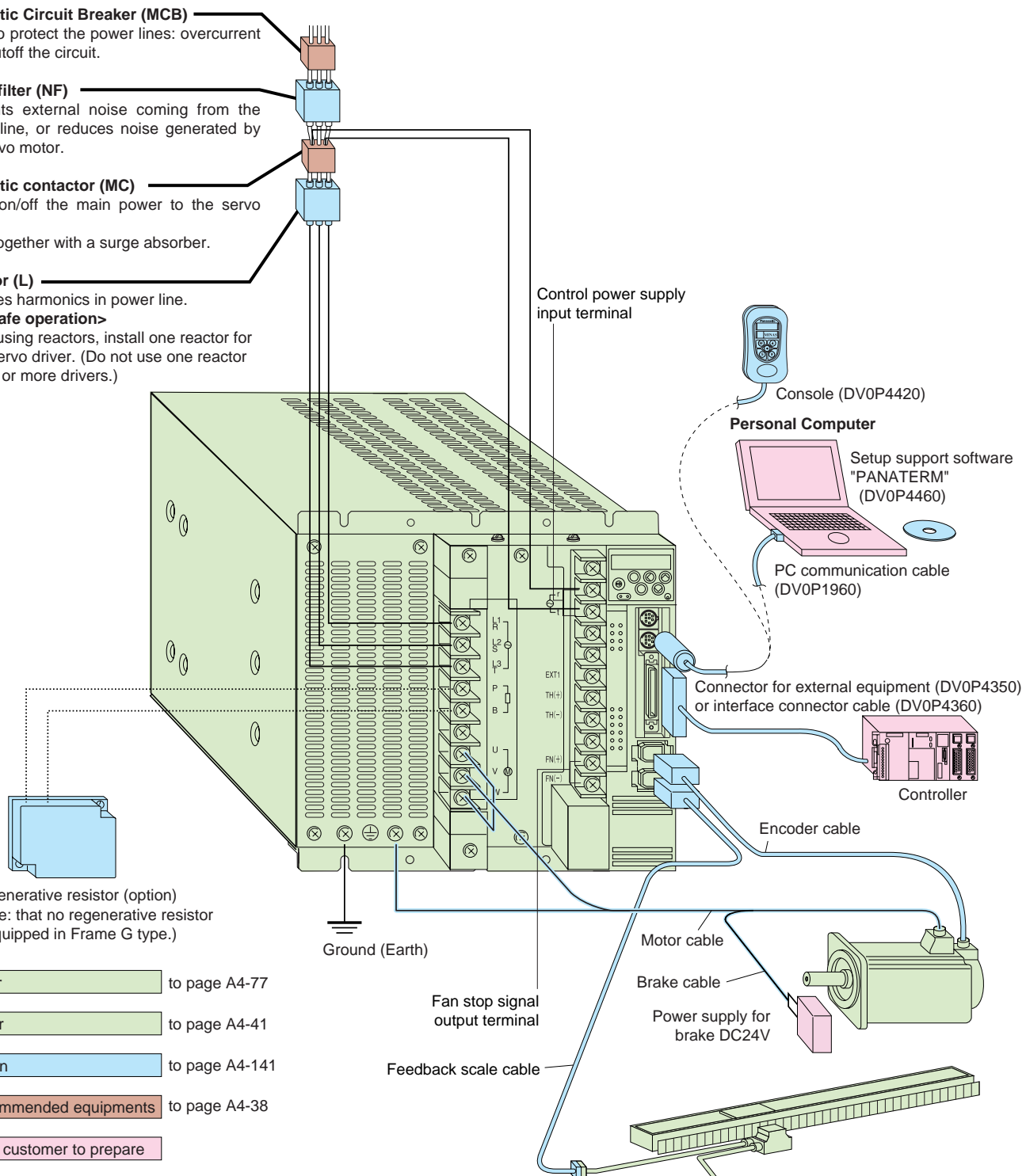
Turns on/off the main power to the servo motor. Used together with a surge absorber.

Reactor (L)

Reduces harmonics in power line.

<For safe operation>

When using reactors, install one reactor for each servo driver. (Do not use one reactor for two or more drivers.)



Regenerative resistor (option)
(Note: that no regenerative resistor is equipped in Frame G type.)

- Motor to page A4-77
- Driver to page A4-41
- Option to page A4-141
- Recommended equipments to page A4-38
- Parts customer to prepare

<Remarks>

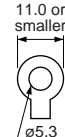
When supplying power for feedback scale from driver, use CS signal power supply output from connector CN X6 (EX5V*1, EXOV*2).

*1 Current consumption of EX5V is 250 mA max.

*2 EXOV is connected to GND of the control circuit connected to CN X5. For wiring, refer to A4-45 and 46.

5 VDC power supply for scaling

● List of recommended peripheral equipments

Power supply voltage	Applicable motor		Power capacity (at rated load)	Circuit breaker (rated current)	Noise filter	Surge absorber	Noise filter (signal)	Magnetic contactor (Contact)	Cable diameter (Main circuit)	Cable diameter (control circuit)	Connector					
	Series	Output														
Single phase, 100V	MSMD	50W	Approx. 0.4kVA	BBW2102 (10A)	DVOP4170	DVOP4190	DVOP1460	BMFT61041N (3P+1a)	0.75mm ² to 2.0mm ² AWG14 to 18	0.75mm ² AWG18	Connection to exclusive connector					
		100W										Approx. 0.5kVA				
	MQMA	200W	Approx. 0.9kVA													
Single phase, 200V	MSMD	50W			Approx. 0.5kVA			DVOP4170				BMFT61542N (3P+1a)	DVOP1460	BMFT61542N (3P+1a)	0.75mm ² to 2.0mm ² AWG14 to 18	0.75mm ² AWG18
		100W	Approx. 0.3kVA													
	MAMA	100W			Approx. 0.5kVA											
	MQMA	200W	Approx. 0.9kVA													
	MQMA	400W		Approx. 0.9kVA												
Single/3-phase, 200V	MAMA	400W	Approx. 0.9kVA		BBW3152 (15A)	DVOP4180	DVOP1460	BMFT61842N (3P+1a)	2.0mm ² AWG14	0.75mm ² AWG18	Connection to exclusive connector					
	MFMA	500W		Approx. 1.1kVA												
	MSMD	750W	Approx. 1.3kVA													
	MAMA	750W		Approx. 1.6kVA												
	MDMA	1.0kW	Approx. 1.8kVA		DVOP4220											
	MHMA	900W		Approx. 2.3kVA												
	MGMA	900W	Approx. 2.3kVA													
	MSMA	1.0kW		Approx. 2.3kVA												
3-phase, 200V	MSMA	1.5kW	Approx. 2.3kVA		BBW3202 (20A)	DVOP4220	DVOP1450	BMF6352N (3P+2a2b)	3.5mm ² AWG12	0.75mm ² AWG18	Terminal block M5 					
	MDMA	2.0kW		Approx. 3.3kVA												
	MHMA	2.0kW	Approx. 3.8kVA													
	MFMA	2.5kW		Approx. 3.8kVA												
	MGMA	2.0kW	Approx. 4.5kVA													
	MSMA	3.0kW		Approx. 4.5kVA												
	MDMA	4.0kW	Approx. 6.0kVA													
	MHMA	4.0kW		Approx. 6.8kVA												
	MFMA	4.5kW	Approx. 6.8kVA													
	MGMA	4.5kW		Approx. 7.5kVA												
	MSMA	5.0kW	Approx. 7.5kVA													
	MDMA	5.0kW		Approx. 9.0kVA												
	MHMA	5.0kW	Approx. 11kVA													
	MGMA	6.0kW		Approx. 11kVA												
MDMA	7.5kW	Approx. 11kVA														
MHMA	7.5kW		Approx. 11kVA													

- Select a single and 3-phase common specifications corresponding to the power supplies.
- Listed circuit breaker and magnetic contactor are manufactured by Panasonic Electric Works.
To conform to EC Directives, install a circuit breaker which conforms to IEC and UL Standards (Listed, (U) marked) between noise filter and power supply without fail.
- For details of noise filter, refer to Page A4-138.

<Remarks>

- Select a circuit breaker and noise filter which match to the capacity of power supply (including a load condition).
- Terminal block and earth terminals
 - Use a copper conductor cables with temperature rating of 60°C or higher.
 - Earth terminals for Frame A to D are M4 and M5 for Frame E to G.
 - Larger tightening torque for screws than the Max. value (M4 : 1.2 N·m, M5 : 2.0 N·m) may damage the terminal block.
 - Mounting screws on the cover of terminal block for frames E to G and screw on acrylic cover of terminal block for frame G should be tightened with 0.2 N·m torque.
- Application of torque larger than 0.2 N·m may damage the thread on the driver.
- Use an earth cable with the same diameter as that of the main circuit cable.
 If the diameter of the main circuit cable is 1.6mm² or less, use an earth cable with a diameter of 1.6mm² (AWG14).
- Use the attached exclusive connector for A to D-frame, and maintain the peeled off length of 8 to 9mm.
- Tighten the screws of the connector, CN X5 for the host controller with the torque of 0.3 to 0.35 N·m.
- Larger torque than 0.35N·m may damage the connector at the driver side.

<Caution>

Do not turn on power without first positively tightening all terminal block screws, otherwise, loose contacts may generate heat (smoking, firing).

Table of Part Numbers and Options

Motor series	Power supply	Rated rotational speed (r/min)	Output (W)	2500P/r, Incremental			17bit, Absolute/Incremental common				2500P/r and 17bit common		
				Motor Note) 1	Rating/Spec. (page)	Encoder cable Note) 2	Motor Note) 1	Rating/Spec. (page)	Encoder cable Note) 2	Encoder cable Note) 2	Driver	Frame symbol	
MAMA [Ultra low inertia]	Single phase 200V	5000	100	MAMA012P1	A4-77	MFECA 0**0EAM	MAMA012S1	A4-77	MFECA 0**0EAE	MFECA 0**0EAD	MADDT1207F	A-frame	
			200	MAMA022P1			MAMA022S1				MBDDT2210F	B-frame	
			400	MAMA042P1			MAMA042S1				MCDDT3520F	C-frame	
			750	MAMA082P1			MAMA082S1				MDDDT5540F	D-frame	
	3-phase, 200V	5000	400	MAMA042P1	MAMA042S1	MCDDT3520F	C-frame						
			750	MAMA082P1	MAMA082S1	MDDDT5540F	D-frame						
MSMD [low inertia]	Single phase 100V	3000	50	MSMD5AZP1	A4-79	MFECA 0**0EAM	MSMD5AZS1	A4-79	MFECA 0**0EAE	MFECA 0**0EAD	MADDT1105F	A-frame	
			100	MSMD011P1			MSMD011S1				MADDT1107F	A-frame	
			200	MSMD021P1			MSMD021S1				MBDDT2110F	B-frame	
			400	MSMD041P1			MSMD041S1				MCDDT3120F	C-frame	
	Single phase 200V	3000	50	MSMD5AZP1	A4-83	MFECA 0**0EAM	MSMD5AZS1	A4-83	MFECA 0**0EAE	MFECA 0**0EAD	MADDT1205F	A-frame	
			100	MSMD012P1			MSMD012S1				MADDT1205F	A-frame	
			200	MSMD022P1			MSMD022S1				MADDT1207F	A-frame	
			400	MSMD042P1			MSMD042S1				MBDDT2210F	B-frame	
			750	MSMD082P1			MSMD082S1				MCDDT3520F	C-frame	
	3-phase, 200V	3000	750	MSMD082P1	MSMD082S1	MCDDT3520F	C-frame						
	MQMA [Low inertia Cube type]	Single phase 100V	3000	100	MQMA011P1	A4-87	MFECA 0**0EAM	MQMA011S1	A4-87	MFECA 0**0EAE	MFECA 0**0EAD	MADDT1107F	A-frame
				200	MQMA021P1			MQMA021S1				MBDDT2110F	B-frame
400				MQMA041P1	MQMA041S1			MCDDT3120F				C-frame	
Single phase 200V		3000	100	MQMA012P1	A4-89	MFECA 0**0EAM	MQMA012S1	A4-89	MFECA 0**0EAE	MFECA 0**0EAD	MADDT1205F	A-frame	
			200	MQMA022P1			MQMA022S1				MADDT1207F	A-frame	
			400	MQMA042P1			MQMA042S1				MBDDT2210F	B-frame	
MSMA [low inertia]	Single phase 200V	3000	1000	MSMA102P1	A4-91	MFECA 0**0ESD	MSMA102S1	A4-91	MFECA 0**0ESE	MFECA 0**0ESD	MDDDT5540F	D-frame	
			1500	MSMA152P1			MSMA152S1				MDDDT5540F	D-frame	
	3-phase, 200V	3000	1000	MSMA102P1			MSMA102S1				MDDDT5540F	D-frame	
			1500	MSMA152P1			MSMA152S1				MDDDT5540F	D-frame	
			2000	MSMA202P1			MSMA202S1				MEDDT7364F	E-frame	
			3000	MSMA302P1			MSMA302S1				MFDDTA390F	F-frame	
			4000	MSMA402P1			MSMA402S1				MFDDTB3A2F	F-frame	
5000	MSMA502P1	MSMA502S1	MFDDTB3A2F	F-frame									
MDMA [Middle inertia]	Single phase 200V	2000	1000	MDMA102P1	A4-95	MFECA 0**0ESD	MDMA102S1	A4-95	MFECA 0**0ESE	MFECA 0**0ESD	MDDDT3530F	D-frame	
			1500	MDMA152P1			MDMA152S1				MDDDT5540F	D-frame	
	3-phase, 200V	2000 Note)3	1000	MDMA102P1			MDMA102S1				MDDDT3530F	D-frame	
			1500	MDMA152P1			MDMA152S1				MDDDT5540F	D-frame	
			2000	MDMA202P1			MDMA202S1				MEDDT7364F	E-frame	
			3000	MDMA302P1			MDMA302S1				MFDDTA390F	F-frame	
			4000	MDMA402P1			MDMA402S1				MFDDTB3A2F	F-frame	
			5000	MDMA502P1			MDMA502S1				MFDDTB3A2F	F-frame	
			7500	MDMA752P1			MDMA752S1				MGDDTC3B4F	G-frame	
			MGMA [Middle inertia Low speed/High torque]	Single phase 200V			1000				900	MGMA092P1	A4-101
900	MGMA092P1	MGMA092S1			MDDDT5540F	D-frame							
3-phase, 200V	1000	2000		MGMA202P1	MGMA202S1	MFDDTA390F	F-frame						
		3000		MGMA302P1	MGMA302S1	MFDDTB3A2F	F-frame						
		4500		MGMA452P1	MGMA452S1	MFDDTB3A2F	F-frame						
		6000		MGMA602P1	MGMA602S1	MGDDTC3B4F	G-frame						
MFMA [Middle inertia Flat type]	Single phase 200V	2000	400	MFMA042P1	A4-105	MFECA 0**0ESD	MFMA042S1	A4-105	MFECA 0**0ESE	MFECA 0**0ESD	MCDDT3520F	C-frame	
			1500	MFMA152P1			MFMA152S1				MDDDT5540F	D-frame	
	3-phase, 200V	2000 Note)3	400	MFMA042P1			MFMA042S1				MCDDT3520F	C-frame	
			1500	MFMA152P1			MFMA152S1				MDDDT5540F	D-frame	
			2500	MFMA252P1			MFMA252S1				MEDDT7364F	E-frame	
			4500	MFMA452P1			MFMA452S1				MFDDTB3A2F	F-frame	
MHMA [High inertia]	Single phase 200V	2000	500	MHMA052P1	A4-109	MFECA 0**0ESD	MHMA052S1	A4-109	MFECA 0**0ESE	MFECA 0**0ESD	MCDDT3520F	C-frame	
			1000	MHMA102P1			MHMA102S1				MDDDT3530F	D-frame	
			1500	MHMA152P1			MHMA152S1				MDDDT5540F	D-frame	
	3-phase, 200V	2000 Note)3	500	MHMA052P1			MHMA052S1				MCDDT3520F	C-frame	
			1000	MHMA102P1			MHMA102S1				MDDDT3530F	D-frame	
			1500	MHMA152P1			MHMA152S1				MDDDT5540F	D-frame	
			2000	MHMA202P1			MHMA202S1				MEDDT7364F	E-frame	
			3000	MHMA302P1			MHMA302S1				MFDDTA390F	F-frame	
			4000	MHMA402P1			MHMA402S1				MFDDTB3A2F	F-frame	
			5000	MHMA502P1			MHMA502S1				MFDDTB3A2F	F-frame	
			7500	MHMA752P1			MHMA752S1				MGDDTC3B4F	G-frame	

Optional parts						
Motor cable Note) 2	Motor cable (with brake) Note) 2	Brake cable Note) 2	Regenerative resistor	Reactor	Noise filter	
MFMC A 0**0EED	—	MFMC B 0**0GET	DV0P4283	DV0P220	DV0P4170	
			DV0P4284	DV0P221	DV0P4180	
			DV0P4283	DV0P220	DV0P4180	
			DV0P4284	DV0P221	DV0P4220	
MFMC A 0**0EED	—	MFMC B 0**0GET	DV0P4280	DV0P227	DV0P4170	
			DV0P4283	DV0P228		
			DV0P4282		DV0P4180	
			DV0P4281	DV0P220		
					DV0P4170	
			DV0P4283	DV0P221	DV0P4180	
MFMC A 0**0EED	—	MFMC B 0**0GET	DV0P4280	DV0P227	DV0P4170	
			DV0P4283	DV0P228		DV0P4180
			DV0P4282	DV0P220		
			DV0P4281		DV0P4170	
			DV0P4283	DV0P221	DV0P4180	
MFMC D 0**2ECD	MFMC A 0**2FCD	—	DV0P4284	DV0P222	DV0P4220	
MFMC D0**2ECT	MFMC A0**2FCT	—	DV0P4285	DV0P223		
MFMC A 0**3ECT	MFMC A 0**3FCT		DV0P4285 x 2 in parallel	DV0P224 DV0P225	DV0P3410	
MFMC D 0**2ECD	MFMC A 0**2FCD	—	DV0P4284	DV0P222	DV0P4220	
MFMC D0**2ECT	MFMC A0**2FCT	—	DV0P4285	DV0P223		
MFMC A 0**3ECT	MFMC A 0**3FCT		DV0P4285 x 2 in parallel	DV0P224 DV0P225	DV0P3410	
			DV0P4285 x 4 in parallel			
MFMC D 0**2ECD	MFMC A 0**2FCD	—	DV0P4284	DV0P222	DV0P4220	
			DV0P4285	DV0P223		
			DV0P4285 x 2 in parallel	DV0P224 DV0P225	DV0P3410	
MFMC A 0**3ECT	MFMC A 0**3FCT	—	DV0P4285 x 4 in parallel			
			DV0P4284	DV0P223		
			DV0P4285	DV0P224	DV0P3410	
MFMC A 0**2ECD	MFMC A 0**2FCD	—	DV0P4283	DV0P220	DV0P4180	
			DV0P4284	DV0P222	DV0P4220	
			DV0P4283	DV0P220	DV0P4180	
			DV0P4284	DV0P222	DV0P4220	
MFMC D 0**3ECT	MFMC A 0**3FCT	—	DV0P4285 x 2 in parallel	DV0P224		
			DV0P4285 x 4 in parallel		DV0P3410	
MFMC D 0**2ECD	MFMC A 0**2FCD	—	DV0P4283	DV0P220	DV0P4180	
			DV0P4284	DV0P222	DV0P4220	
			DV0P4283	DV0P220	DV0P4180	
			DV0P4284	DV0P222	DV0P4220	
			DV0P4285	DV0P224		
			DV0P4285 x 2 in parallel		DV0P3410	
MFMC A 0**3ECT	MFMC A 0**3FCT	—	DV0P4283	DV0P220	DV0P4180	
			DV0P4284	DV0P222	DV0P4220	
			DV0P4283	DV0P220	DV0P4180	
			DV0P4284	DV0P222	DV0P4220	
		—	DV0P4285	DV0P224		
			DV0P4285 x 2 in parallel	DV0P225	DV0P3410	
		—	DV0P4285 x 4 in parallel			

● Carrying page

Options		Part No.	Carrying page
Technical reference	Japanese	DV0PM20008	—
	English	DV0PM20009	—
Console		DV0P4420	A4-152
Setup support software, PANATERM	Japanese	DV0P4460	A4-151
	English		
RS232 communication cable (for connection with PC)		DV0P1960	A4-147
RS485 communication cable (for connection with PC)	L=200mm	DV0P1970	A4-147
	L=500mm	DV0P1971	
	L=1000mm	DV0P1972	
Interface cable		DV0P4360	A4-147
Connector kit for external equipment		DV0P4350	A4-146
Connector kit for motor and encoder		DV0P4290	A4-148
		DV0P4380	
		DV0P4310	
		DV0P4320	A4-149
		DV0P4330	
		DV0P4340	
		DV0PM20005	A4-150
		DV0PM20006	
Connector kit for absolute encoder		DV0PM20010	A4-150
Battery for absolute encoder		DV0P2990	A4-154
Mounting bracket	Frame A	DV0P4271	A4-151
	Frame B	DV0P4272	
	Frame C	DV0P4273	
	Frame D	DV0P4274	
Encoder cable	MFECA0**0EAD		A4-143
	MFECA0**0EAE		
	MFECA0**0EAM		
	MFECA0**0ESD		
Motor cable	MFECA0**0ESE		A4-144
	MFMC A0**0EED		
	MFMC A0**2ECD		
	MFMC A0**3ECT		
	MFMC D0**2ECD		
Motor cable (with brake)	MFMC D0**2ECT		A4-145
	MFMC D0**3ECT		
	MFMC A0**2FCD		
	MFMC A0**2FCT		
Brake cable		MFMC B0**0GET	A4-145
Regenerative resistor	50 Ω, 25W	DV0P4280	A4-153
	100 Ω, 25W	DV0P4281	
	25 Ω, 50W	DV0P4282	
	50 Ω, 50W	DV0P4283	
	30 Ω, 100W	DV0P4284	
	20 Ω, 130W	DV0P4285	
Reactor		DV0P220 to DV0P228	A4-152
Noise filter		DV0P4170 DV0P4180 DV0P4220 DV0P3410	A4-138
Surge absorber	Single phase 100V, 200V	DV0P4190	A4-139
	3-phase 200V	DV0P1450	
Noise filter for signal wire		DV0P1460	A4-139

Note) 1. □ represents the motor structure.

Note) 2. ** represents the cable length (specified value)
For details, refer to cable specifications (A4-141).

Note) 3. 7.5kW output type: 1500(r/min)